# Distribution-free inference on the extremum of conditional expectations via classification

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## 1 Problem setup

Assume  $(X_1, Y_1), \ldots, (X_n, Y_n)$  are i.i.d. random vectors taking values in  $\mathcal{X} \times \mathcal{Y}$  where  $\mathcal{Y} \subset \mathbb{R}$ . Let (X, Y) denote a generic random vector drawn from the same distribution and  $f(x) = \mathbb{E}[Y \mid X = x]$  denote the conditional expectation and

$$f_{\min} = \inf_{x \in \mathcal{X}} f(x), \quad f_{\max} = \sup_{x \in \mathcal{X}} f(x)$$

denote the infimum and supremum of f(x). By symmetry, we only focus on making inferential claims on  $f_{\min}$ . The goal of this note is to obtain an upper confidence bound  $\hat{f}_{\min}$  on  $f_{\min}$  such that

$$\mathbb{P}(f_{\min} \le \hat{f}_{\min}) \ge 1 - \alpha. \tag{1}$$

where  $\alpha$  is the target Type-I error. In particular, we want the guarantee (1) to hold in finite samples without any assumption on f(x), in which case no consistent estimate of f(x) is guaranteed to exist. Moreover, we want the method to be able to wrap around any estimator of f(x) so that one can apply flexible machine learning algorithms without worrying about potential failure modes. It is not hard to see that no nontrivial lower confidence bound on  $f_{\min}$  exists without assumptions on f since a perturbation of f(x) in a tiny region can change  $f_{\min}$  substantially while has little effect on the observed values.

## 2 Preliminaries

#### 2.1 Covariate standardization

As in Lei et al. [2021], we first split the data into two folds and compute an estimate of the conditional expectation  $\hat{f}(\cdot)$  on the first fold of data using an arbitrary method. With a slight abuse of notation, we let the second fold of data be  $(X_1, Y_1), \ldots, (X_n, Y_n)$ . The following result shows that transforming  $X_i$  never reduces  $f_{\min}$ .

**Proposition 1.** For any estimate  $\hat{f}$  that is independent of  $(X_i, Y_i)_{i=1}^n$ ,

 $f_{\min} \leq \mathbb{E}[Y \mid \hat{f}(X)], \quad almost \ surrely.$ 

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Let  $Z_i = \hat{f}(X_i)$ . Then we are left to find an upper confidence bound for  $g_{\min} \triangleq \inf_{z \in \mathbb{R}} g(z)$  where

$$g(z) = \mathbb{E}[Y \mid Z = z].$$

Throughout the rest of the note, we will construct upper confidence bounds on  $g_{\min}$ .

#### 2.2 Inverting hypothesis tests

When Y is binary, the classification-error (CE) O-value in Lei et al. [2021] only works for  $\inf_x \min\{f(x), 1 - f(x)\}$  and does not directly apply to  $\inf_x f(x)$ . For the latter estimand, we will take a somewhat different strategy by exploiting the duality between confidence intervals and hypothesis testing. Specifically, for any  $c \in \mathbb{R}$ , consider the null hypothesis  $H_0(c) : g_{\min} \geq c$ . Suppose that, for each  $c \in \mathbb{R}$ , we find a test  $\phi_c$  that maps the data to  $\{0, 1\}$  such that

$$\mathbb{P}_{H_0(c)}(\phi_c = 1) \le \alpha.$$

When  $\phi_c$  is monotonic in the sense that  $\phi_{c_1} \leq \phi_{c_2}$  almost surely for any  $c_1 < c_2$  (i.e.,  $H_0(c_2)$  is rejected if  $H_0(c_1)$  is so), an upper confidence bound can be obtained by simply inverting the test, i.e.,

$$\hat{f}_{\min} = \inf\{c \in \mathbb{R} : \phi_c = 1\}.$$
(2)

However, for the problem considered in this note, it is unclear how to construct a monotonic decision. When  $\phi_c$  is not guaranteed to be monotonic, we can instead define

$$\hat{f}_{\min} = \inf\{c : \phi_{c'} = 1, \ \forall c' \ge c\}.$$
 (3)

The following result shows that it is a valid upper confidence bound.

**Proposition 2.** If  $\mathbb{P}_{H_0(c)}(\phi_c = 1) \leq \alpha$  for any  $c \in \mathbb{R}$ ,

$$\mathbb{P}\left(f_{\min} \le \hat{f}_{\min}\right) \ge 1 - \alpha.$$

*Proof.* By definition, if  $f_{\min} > \hat{f}_{\min}$ ,  $\phi_{f_{\min}} = 1$ . Since  $H_0(f_{\min})$  is true,

$$\mathbb{P}\left(f_{\min} > \hat{f}_{\min}\right) \leq \mathbb{P}\left(\phi_{f_{\min}} = 1\right) = \mathbb{P}_{H_0(f_{\min})}\left(\phi_{f_{\min}} = 1\right) \leq \alpha.$$

In some cases, (3) is hard to compute because it requires the entire path on the right of c. Instead, we can start by discretizing c into a grid  $0 = c_0 < c_1 < \ldots < c_N < c_{N+1} = 1$  and then define

$$\hat{f}_{\min} = c_{\hat{j}}, \quad \hat{j} = \min\left\{j : \phi_{c_{j'}} = 1, \ j' \ge j\right\}.$$
 (4)

This is equivalent to apply the fixed sequence test that has over 35 years of history in medical statistics [Sonnemann et al., 1986, Bauer, 1991]. The benefit is that it involves absolutely no multiple testing adjustment and the test  $\phi_c$  is just required to be pointwise valid for  $H_0(c)$ . The number of grid points is entirely driven by the computation budget.

Here we provide a self-contained proof without resorting to the general argument.

**Proposition 3.** Proposition 2 holds for the upper confidence bound defined in (4).

*Proof.* Let  $j_0 = \min\{j : c_j \ge f_{\min}\}$ . Then  $H_0(c_{j_0})$  holds and

$$\mathbb{P}(c_{\hat{j}} < f_{\min}) = \mathbb{P}(\hat{j} < j_0) \le \mathbb{P}(\phi_{j_0} = 1) = \mathbb{P}_{H_0(c_{j_0})}(\phi_{j_0} = 1) \le \alpha$$

In the following sections, we will construct valid tests for  $H_0(c)$  with a fixed  $c \in \mathbb{R}$ .

## 3 Method

#### 3.1 Binary outcomes

In this subsection we assume  $Y_i$  is binary. Let  $Y_{(i)}$  be the outcome corresponding to the *i*-th largest Z's, i.e.,  $Y_{(i)} = Y_{R_i}$  where  $Z_{R_1} \leq Z_{R_2} \leq \ldots \leq Z_{R_n}$ . Conditional on  $\{Z_1, \ldots, Z_n\}$ ,  $Y_{(1)}, \ldots, Y_{(n)}$  are independent Bernoulli variables. Under  $H_0(c)$ , for any entrywise increasing function  $u : [0, 1]^n \to \mathbb{R}$ 

$$u(Y_{(1)}, \dots, Y_{(n)}) \succeq u(B_1(c), \dots, B_n(c))$$
 (5)

where  $B_i(c) \stackrel{i.i.d.}{\sim} \operatorname{Ber}(c)$  and  $\succeq$  denotes stochastic dominance. Let

$$q_n(\alpha, c; u) = \sup\left\{x : \mathbb{P}(u(B_1(c), \dots, B_n(c)) \le x) < \alpha\right\}.$$

For any given u,  $q_n(\alpha, c; u)$  can be computed to any acculation by the Monte-Carlo method. Then we can define a valid test for  $H_0(c)$  as

$$\phi_c = I \{ u(Y_{(1)}, \dots, Y_{(n)}) \le q_n(\alpha, c; u) \}.$$

One reasonable option for u is

$$u(y_1, \dots, y_n) = \min_{k \in \{1, \dots, n\}} \frac{y_1 + \dots + y_k}{k}.$$
 (6)

A shortcoming of this test statistic is that it could be dominated by the first few observations (e.g.,  $y_1 = 0$ ). Another option is

$$u_f(y_1, \dots, y_n) = \max_{n/f(n) \le k \le n} \frac{S_k}{\sqrt{kc(1-c)}}, \quad \text{where } S_k = \sum_{i=1}^k (y_i - c)$$
(7)

for some  $f(n) \in [1, n]$ . In practice, one can simply choose f(n) = n. Unlike (6), the maximizer of (7) diverges, thereby allowing the statistic to account for a majority of observations. Furthermore, the critical value can be approximated by a version of Darling-Erdös theorem.

**Proposition 4.** [Berkes and Weber [2006]] Assume that  $B_1(c), \ldots, B_n(c) \stackrel{i.i.d.}{\sim} Ber(c)$ . As  $n \to \infty$ ,

$$a_{n,f}(u_f(B_1(c),\ldots,B_n(c))-b_{n,f}) \xrightarrow{a} H,$$

where

$$a_{n,f} = \sqrt{2\log\log f(n)}, \ b_{n,f} = a_n + \frac{\log\log\log f(n) - \log 4\pi}{2a_n},$$

and H is the distribution with  $CDF \exp\{-\exp\{-x\}\}$ . In particular,

$$\lim_{n \to \infty} \mathbb{P}\left(u_f(B_1(c), \dots, B_n(c)) \le b_{n,f} - a_{n,f}^{-1} \log \log \left(\frac{1}{\alpha}\right)\right) = \alpha.$$

#### **3.2** Bounded outcomes

In this subsection, we consider the case of bounded outcomes. Without loss of generality, we assume  $Y_i \in [0, 1]$ . Let

$$\mathcal{E}(\eta) = \mathbb{E}[(1-Y)I(Z>\eta)] + \mathbb{E}[YI(Z\le\eta)] \cdot \frac{1}{1+c} + \mathbb{E}[YI(Z>\eta)] \cdot \frac{c}{1+c}.$$

Then we can rewrite  $\mathcal{E}(\eta)$  as

$$\begin{split} \mathcal{E}(\eta) &= \mathbb{E}\left[\left(1 - Y + \frac{c}{1+c}Y\right)I(Z > \eta) + \frac{1}{1+c}YI(Z \le \eta)\right] \\ &= \mathbb{E}\left[\mathbb{E}\left[\left(1 - \frac{1}{1+c}Y\right)I(Z > \eta) + \frac{1}{1+c}YI(Z \le \eta) \mid Z\right]\right] \\ &= \mathbb{E}\left[\mathbb{E}\left[\left(1 - \frac{1}{1+c}g(Z)\right)I(Z > \eta) + \frac{1}{1+c}g(Z)I(Z \le \eta) \mid Z\right]\right]. \end{split}$$

Since  $I(Z > \eta) + I(Z \le \eta) = 1$ ,

$$\mathcal{E}(\eta) \ge \mathbb{E}\left[\min\left\{1 - \frac{1}{1+c}g(Z), \frac{1}{1+c}g(Z)\right\}\right].$$

Under  $H_0(c)$ , it is clear that

$$\mathcal{E}(\eta) \ge \frac{c}{1+c}.$$

This yields a testable implication. We estimate  $\mathcal{E}(\eta)$  by the empirical analogue:

$$\hat{\mathcal{E}}(\eta) \triangleq \frac{1}{n} \sum_{i=1}^{n} \left\{ I(Y_i = 0, Z_i \ge \eta) + I(Y_i = 1, Z_i < \eta) \cdot \frac{1}{1+c} + I(Y_i = 1, Z_i \ge \eta) \cdot \frac{c}{1+c} \right\}.$$
(8)

Note that

$$I(Y_i = 0, Z_i \ge \eta) + I(Y_i = 1, Z_i < \eta) \cdot \frac{1}{1+c} + I(Y_i = 1, Z_i \ge \eta) \cdot \frac{c}{1+c} \in [0, 1].$$

By Theorem 1 in Appendix A, we can compute  $t_n(\alpha, \xi)$  by inverting the tail probability bound such that with probability  $1 - \alpha$ ,

$$\sup_{\eta \in [0,1]} \frac{\mathcal{E}(\eta) - \hat{\mathcal{E}}(\eta)}{\sqrt{\mathcal{E}(\eta) + \xi}} \le t_n(\alpha, \xi).$$

In particular, we can choose  $\xi$  based on the strategy discussed in Appendix F.3 of Angelopoulos et al. [2021]. As a result, with probability  $1 - \alpha$ ,

$$\mathcal{E}(\eta) \le \hat{\mathcal{E}}(\eta) + \frac{t_n^2(\alpha,\xi)}{2} + t_n(\alpha,\xi)\sqrt{\hat{\mathcal{E}}(\eta) + \xi + \frac{t_n^2(\alpha,\xi)}{4}}, \quad \forall \eta \in [0,1]$$

This implies a valid test for  $H_0(c)$ :

$$\phi_{c} = I\left(\inf_{\eta \in [0,1]} \hat{\mathcal{E}}(\eta) + \frac{t_{n}^{2}(\alpha,\xi)}{2} + t_{n}(\alpha,\xi)\sqrt{\hat{\mathcal{E}}(\eta) + \xi + \frac{t_{n}^{2}(\alpha,\xi)}{4}} < \frac{c}{1+c}\right).$$

Note that  $\phi_c$  is non-monotonic in c. In addition,  $\phi_c$  is not easy to compute when  $\xi$  is chosen based on the technique described in Appendix F.3 of Angelopoulos et al. [2021] which depends on c intricately. Nonetheless, we can compute an upper bound by (4).

## References

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## A A computable concentration inequality for self-normalized empirical processes

This section reviews the concentration inequality derived in Appendix G of Angelopoulos et al. [2021]. It is typically tighter than all other computable concentration inequalities (that is, the ones with explicit constants) in the past 50 years.

Let  $W_1, \ldots, W_n$  be i.i.d. random variables and  $S(\lambda; w)$  be a function of w indexed by a (potentially multivariate) parameter  $\lambda \in \Lambda$  that takes value in [0, 1] for any  $\lambda$  and w. In our context,  $\lambda = \eta, W_i = (Y_i, Z_i)$  and

$$S(\lambda; W_i) = I(Y_i = 0, Z_i \ge \xi) + I(Y_i = 1, Z_i < \xi) \cdot \frac{1}{1+c} + I(Y_i = 1, Z_i \ge \xi) \cdot \frac{c}{1+c}$$

Further let

$$\hat{s}_n(\lambda) = \frac{1}{n} \sum_{i=1}^n S(\lambda; W_i), \quad s(\lambda) = \mathbb{E}[S(\lambda; W_i)].$$
(9)

Furthermore, we define  $\Delta(n)$  as the

$$\Delta(n) = \sup_{z_1,\dots,z_n} \left| \left\{ \{ S(\lambda; z_1), \dots, S(\lambda; z_n) \} : \lambda \in \Lambda \right\} \right|.$$
(10)

In the literature,  $\log \Delta(n)$  is often referred to as the growth function ([Vapnik, 1995, Section 2]).

**Theorem 1.** For any  $\xi \ge 0$ ,

$$\mathbb{P}\left(\sup_{\lambda\in\Lambda}\frac{s(\lambda)-\hat{s}_n(\lambda)}{\sqrt{s(\lambda)+\xi}}\geq t\right) \\ \leq \min\left\{\inf_{\gamma\in(0,1),n'\in\mathbb{Z}^+}\frac{\Delta(n+n')\exp\{-g_2(t;n,n',\gamma,\kappa^-)\}}{1-\exp\{-g_1(t;n',\gamma,\xi)\}},\inf_{\gamma\in(0,1)}\frac{\Delta(2n)\tilde{g}\left(\sqrt{\frac{n(1+\xi)}{2}}(1-\gamma)t\right)}{1-\exp\{-g_1(t;n,\gamma,\xi)\}}\right\},$$

where

$$g_1(t;n',\gamma,\kappa) = \max\left\{\frac{n't^2}{2}\frac{\gamma^2}{1+\gamma^2 t^2/36\kappa}, \log\left(\frac{n't^2\gamma^2}{(\sqrt{1+\kappa}-\sqrt{\kappa})^2}\right)\right\},\$$

$$g_2(t;n,n',\gamma,\kappa) = \frac{nt^2}{2}\left(\frac{n'}{n+n'}\right)^2\frac{(1-\gamma)^2}{1+(1-\gamma)^2 t^2/36\kappa},\$$

$$\kappa^+ = \xi + \frac{t^2}{2} + t\sqrt{\frac{t^2}{4}+\xi}, \quad \kappa^- = \xi + \frac{n+\gamma n'}{n+n'}\sqrt{\kappa^+},$$

and  $\tilde{g}(x) = \min\{\tilde{g}_1(x), \tilde{g}_2(x), \tilde{g}_3(x)\}$  with

$$\begin{split} \tilde{g}_1(x) &= c_1(1 - \Phi(x)), \quad c_1 = 1/4(1 - \Phi(\sqrt{2})) \approx 3.178, \\ \tilde{g}_2(x) &= 1 - \Phi(x) + \frac{c_2}{9 + x^2} \exp\left\{-\frac{x^2}{2}\right\}, \quad c_2 = 5\sqrt{e}(2\Phi(1) - 1) \approx 5.628, \\ \tilde{g}_3(x) &= \exp\left\{-\frac{x^2}{2}\right\}. \end{split}$$